

On the effect of saturation factor and effective contact rate on the transmission dynamics of Ebola

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Abstract:

In this study we propose a modified SEQIR model to further investigate the dynamics of Ebola virus. A deterministic and stochastic framework was considered to verify the implication(s) of saturation coefficient on the transmission dynamics of Ebola. Necessary qualitative analysis: Existence and Uniqueness, boundedness, local and global stability, at disease - free equilibrium were considered to validate the epidemiological feasibility of the model. The reproduction number was found to be less than unity. Furthermore, the effective contact rate of the disease and saturation coefficient rates were varied within the model to validate the effects of these parameters on the transmission dynamics of the infection and results from numerical simulations using assumed (fitted) values indicate the overall effects of the saturation coefficient rate in phasing out the disease in the long run when moderated.

Keywords: Ebola virus disease (EVD), saturation effects, stability analysis, stochastic differential equation.

1. Introduction

he Ebola virus disease (EVD), which was first identified in 1997 and is named after a river in former Zaire is a severe viral hemorrhagic infectious fever. It is a member of the RNA virus family known as filovirus and research has demonstrated that fruit bats in the Pteropodidae family-known to be the virus's natural host-are the conduit for the virus's spread. Personal contact with body tissues, semen or fluids, from infectious individuals dead or alive is the primary method by which the Ebola virus disease is transmitted [1-3]. EVD causes symptoms like the flu initially, but it soon progresses to external and internal bleeding, rash, diarrhoea and vomiting. Once inside the body, the virus begins to attack cells of the immune system, which are liver and blood cells, which are responsible for protecting the body from infection. Those who are infected with the virus become contagious after 21 days during incubation [4]. The virus targets the liver and kidneys, two vital organs, as the fever rises. This results in significant bleeding, tissue destruction, respiratory arrest, shocks, and ultimately death. About 50% to 90% of those infected die between 10 days after acquiring the disease, according to the World Health Organization [5-8]. Due to two distinct Ebola virus strains (Ebola Sudan and Ebola Zaire) that were discovered in those regions, twelve Ebola outbreaks were documented in 2003 in Gabon, Sudan, Uganda and Congo. This nation includes Guinea, Nigeria, Sierra Leone, Senegal, Liberia, Mali, United States, Spain and the United Kingdom reported the biggest outbreaks. Throughout this era, there were 26,724 cases of infections and 11065 deaths [9-13]. Six countries Nigeria, Mali, Senegal, the United Kingdom, Spain, and the United States have been declared free of the Ebola virus illness; nonetheless, there is a recently reported case of Ebola from a country where

the disease is widely and actively transmitted [14]. In September 2022, the Uganda Ministry of Health, along with AFRO and WHO, verified the EVD outbreak in Mubende Region. The type of EVD that was confirmed was Sudan virus disease (SVD), and a death case was reported. This case involved a 24-year-old man who lived in a village called Ngabano, Madudu in the District of Mubende. It was seen that the guy had a high temperature, stomach discomfort, diarrhea, and blood in his vomit. There were 142 confirmed cases, 87 recovered cases, and 55 deaths (CFR: 39%) overall [3, 15].

Differential equations have been vital tools in describing the dynamics of infectious diseases [9-20]. and many more dynamical concepts in sciences and engineering. Results from many of this research have positively affected prompt responses to diseases outbreaks [21 - 24].

A significant contribution to the modelling of infectious disease types and transmission was made by Kermack and Mckendrick [22]. This concept was called the SIR model, and several researchers have since expanded it and used it to study a variety of infectious illnesses [16-26].

Researchers are very interested in the mechanics of the transmission of Ebola fever sickness. Astacio and colleagues employed the SEIR and SIR models to mimic two Ebola outbreaks on the one that transpired in Yambuku, Zaire, in 1976 and Kikwit, Zaire, in 1995 [24-25]. The behavior of these models was estimated using the per-capita effective contact rate of a person contracting the disease and the per-capita death rate of infected individuals. The basic reproductive number $R_{\rm 0}$, determines how infectiously the disease invades a community [9-13, 16-19, 26]. The study asserted that Ebola is not as infectious as previously thought and that the results of their simulations would provide scientists with information that will

enable them to lessen the number of people who may die in the event of future outbreaks. To analyse the stability of the infection-Free Equilibrium State and manage the dynamics of Ebola transmission, some authors created models. They also devised optimum control mechanisms for monkey pox [27-28].

Despite existing literature immensely addressed transmission dynamics and possible control measures to the invasion of the deadly infection, the implications of extensive study on the transmission dynamics of the disease to further propose effective intervention measures to tame the deadly disease cannot be over emphasized. Hence, we present a modified SEOIR to further emphasize the overall implications of the contact rate and saturation coefficient on the transmission dynamics of Ebola virus.

2.0 MATERIALS AND METHODS

2. 1. Model Formulation

To properly understand the dynamics of the Ebola virus infection, the model made some assumptions in the modification of five compartmental classes which are S= Susceptible class, E = Exposed class, Q = Quarantine, I= Infected class and R = recovered compartment, where all classes are equipped with biological parameter.

$$\Psi = \frac{\beta IS}{1+aI}$$

Is the model force of infection, where β is the effective contact rate, I is the infection compartment, S is the susceptible class, and a is the saturation factor to lessen the infection severity?

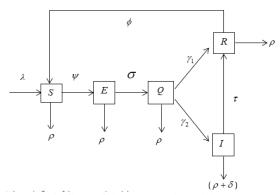


Figure 1: Schematic flow of the proposed model

The following sets of equations are derived from the schematic flow (Figure 1).

$$\begin{split} \frac{dS}{dt} &= \lambda - \rho S - \Psi S + \phi R \\ \frac{dE}{dt} &= \Psi S - \rho E - \sigma E \\ \frac{dQ}{dt} &= \sigma E - Q(\gamma_1 + \gamma_2) - \rho Q \\ \frac{dI}{dt} &= \gamma_2 Q - I(\rho + \delta) - \tau I \\ \frac{dR}{dt} &= \gamma_1 Q + \tau I - R\rho - \phi R \\ S(t) &\geq 0, E(t) \geq 0, Q(t) \geq 0, I(t) \geq 0, R(t) \geq 0. \end{split}$$

The following sets of equations are derived from the schematic flow (Figure 1).

Table 1. Parameters values used in the numerical validation

Parameters	Description	Value	Sources
λ	Rate of recruitment	0.09	Assumed
Ψ	Force of infection	0.091196	Assumed
σ	Progression rate from		
	Exposed to quarantine	0.010	Assumed
ρ	Natural death rate	0.0017256	Assumed
γ_1	Progress rate from		
	quarantine to recover	0.05075	Assumed
Y2	Progression rate from quarantine		
	to infected	0.0087	Assumed
ϕ	Relapse rate	0.2062	Assumed
a	Saturation factor	0 - 1	Calibrated
β	Effective contact rate	0 - 1	Calibrated
τ	Rate of recovery		
	from infected class	0.005	Loyinmi et al., 2022
δ	Disease induced death	0.00074	Loyinmi et al., 2022

2.2 Qualitative Analysis of the proposed model

2.2.1. Existence and Uniqueness of solution

Using the Lipchitz condition, from the systems of equation generated from the schematic diagram.

$$A_{1} = \lambda - \rho S - \Psi S + \varphi R$$

$$A_{2} = \Psi S - \rho E - \sigma E$$

$$A_{3} = \sigma E - Q(\gamma_{1} + \gamma_{2}) - \rho Q$$

$$A_{4} = \gamma_{2}Q - I(\rho + \delta) - \tau I$$

$$A_{5} = \gamma_{1}Q + I - R\rho - \phi R$$
(2)

Theorem 1: Let K denote the region $0 \le \chi \le M$, then the systems of equations (2) possess a unique solution if and only if $\frac{\partial G_i}{\partial b_i}$ are continuous and bounded in K, for $i \neq j$

Proof

$$\begin{split} &\left|\frac{\partial A_1}{\partial S}\right| = \left|-\left(\Psi+\rho\right)\right| \prec \infty, \\ &\left|\frac{\partial A_1}{\partial I}\right| = \left|0\right| \prec \infty, \\ &\left|\frac{\partial A_1}{\partial R}\right| = \left|\rho\right| \prec \infty, \\ &\left|\frac{\partial A_1}{\partial E}\right| = \left|0\right| \prec \infty, \\ &\left|\frac{\partial A_2}{\partial S}\right| = \left|-\left(\Psi\right)\right| \prec \infty, \\ &\left|\frac{\partial A_2}{\partial I}\right| = \left|0\right| \prec \infty, \\ &\left|\frac{\partial A_2}{\partial R}\right| = \left|0\right| \prec \infty, \\ &\left|\frac{\partial A_2}{\partial E}\right| = \left|\rho\right| \prec \infty, \\ &\left|\frac{\partial A_2}{\partial Q}\right| = \left|\rho\right| \prec \infty, \\ &\left|\frac{\partial A_2}{\partial Q}\right| = \left|\rho\right| \prec \infty, \\ &\left|\frac{\partial A_3}{\partial I}\right| = \left|\rho$$

Clearly from the partial derivative above of system (2), the solutions to the systems of equations exist, unique and remain bounded.

2.2.2. Boundedness of solution

Here, we examine and confirm the mathematical and epidemiological soundness of the model. Additionally, that the relevant partitions' solutions are non-negative.

The total population of human compartment.

$$N = S + E + Q + I + R \tag{3}$$

From the derivatives of sums, we have
$$\frac{dN}{dt} = \frac{dS}{dt} + \frac{dE}{dt} + \frac{dQ}{dt} + \frac{dI}{dt} + \frac{dR}{dt}$$
 (4)

Simplifying (4) we obtain;

$$\frac{dN}{dt} = \lambda - \rho(N) = \lambda - \rho N \rightarrow \frac{dN}{dt} + \rho N = \lambda,$$

$$N(t) = \frac{\lambda_H}{\mu_H} + ce^{-\mu_H t}$$

which at $t \rightarrow \infty$ becomes

$$N(t) \le \frac{\lambda}{\rho} \tag{5}$$

From (5) we have demonstrated the epidemiological boundedness of the model.

2.3 Fundamental reproduction number

This number represents the typical number of secondary infections in the E(t) compartment in a fully vulnerable group that were caused by an infected person already in the I(t). The "next generation matrix method" will be used to calculate R_0 . Let F represent the matrix of a new infection while V is the matrix of secondary infection.

$$F_1 = \Psi S$$
, $F_2 = 0$

$$\begin{bmatrix} \frac{\partial F_1}{\partial E} & \frac{\partial F_2}{\partial I} \\ \frac{\partial F_2}{\partial E} & \frac{\partial F_2}{\partial I} \end{bmatrix} = \begin{bmatrix} 0 & \beta S \\ 0 & 0 \end{bmatrix}$$

$$V_1 = -(\mu + \theta)E$$
, $V_2 = \theta E - (\mu + \delta + \tau)I$

$$\begin{bmatrix} \frac{\partial V_1}{\partial E} & \frac{\partial V_1}{\partial I} \\ \frac{\partial V_2}{\partial E} & \frac{\partial V_2}{\partial I} \end{bmatrix} = \begin{bmatrix} -(\mu + \theta) & 0 \\ \theta & -(\mu + \delta + \tau) \end{bmatrix}$$

Using $R_0 = \chi(FV^{-1})$, where χ is the spectral radius of FV^{-1} ,

$$V^{-1} = \frac{Adj(V)}{|V|}, \ Adj(V) = \begin{bmatrix} -\left(\rho + \delta + \tau\right) & 0 \\ \sigma & -\left(\rho + \sigma\right) \end{bmatrix}, \ \left|V\right| = \left|\left(\rho + \delta + \tau\right)(\rho + \sigma)\right|$$

Hence
$$V^{-1} = \begin{bmatrix} \frac{-1}{(\rho + \sigma)} & 0\\ \frac{-\sigma}{(\rho + \delta + \tau)(\rho + \sigma)} & \frac{-1}{(\rho + \delta + \tau)} \end{bmatrix}$$

$$FV^{-1} = \begin{bmatrix} -\beta\sigma S & -\beta S \\ (\rho + \delta + \tau)(\rho + \sigma) & (\rho + \delta + \tau) \\ 0 & 0 \end{bmatrix}$$

Where k is the Eigenvalue;

$$|FV^{-1} - kI| = \begin{vmatrix} -\beta\sigma S \\ (\rho + \delta + \tau)(\rho + \sigma) - k & \frac{-\beta S}{(\rho + \delta + \tau)} \\ 0 & 0 - k \end{vmatrix}$$

The spectral radius of
$$FV^{-1}$$
 is $\frac{\beta \sigma S}{(\rho + \delta + \tau)(\rho + \sigma)}$. (6)

Note that $S = \frac{\lambda}{\mu}$, replacing S, the reproduction number

become
$$R_0 = \frac{\beta \sigma \lambda}{\rho(\rho + \delta + \tau)(\rho + \sigma)}$$
 (7)

2.4. Local Stability Analysis.

Theorem 3: If $R_0 < 1$, then the model is locally asymptotically stable. **Proof**

Let.

$$\begin{split} F_1 &= \lambda - \rho S - \Psi S + \varphi R, \ F_2 = \Psi S - \rho E - \sigma E, \ F_3 = \sigma E - Q(\gamma_1 + \gamma_2) - \rho Q \\ F_4 &= \gamma_2 Q - I(\rho + \delta) - \tau I, \ F_4 = \gamma_1 Q + \tau I - \rho R - \phi R \end{split}$$

Using the Jacobi function as I(S, E, Q, I, R)

$$J = \begin{bmatrix} \frac{\partial F_1}{\partial S} & \frac{\partial F_1}{\partial E} & \frac{\partial F_1}{\partial Q} & \frac{\partial F_1}{\partial I} & \frac{\partial F_1}{\partial R} \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial F_5}{\partial S} & \frac{\partial F_5}{\partial E} & \frac{\partial F_5}{\partial Q} & \frac{\partial F_5}{\partial I} & \frac{\partial F_5}{\partial R} \end{bmatrix}$$

$$(8)$$

$$J = \begin{bmatrix} -(\rho + \Psi) & 0 & 0 & \beta S & \phi \\ \Psi & -(\sigma + \rho) & 0 & \beta S & 0 \\ 0 & \sigma & -(\gamma_1 + \gamma_2 + \rho) & 0 & 0 \\ 0 & 0 & \gamma_2 & -(\rho + \delta + \tau) & 0 \\ 0 & 0 & \gamma_1 & \tau & -(\rho + \phi) \end{bmatrix}$$
(9)

At disease free equilibrium

$$J(E^{0}) = \begin{bmatrix} -\rho & 0 & 0 & \beta S & \phi \\ 0 & -(\sigma+\rho) & 0 & \beta S & 0 \\ 0 & \sigma & -(\gamma_{1}+\gamma_{2}+\rho) & 0 & 0 \\ 0 & 0 & \gamma_{2} & -(\rho+\delta+\tau) & 0 \\ 0 & 0 & \gamma_{1} & \tau & -(\rho+\phi) \end{bmatrix}$$
(10)

Solving (10) steadily using Row reduction and Gaussian elimination method we obtain.

$$\begin{split} k_1 &= -\rho, & k_2 &= -(\gamma_1 + \gamma_2 + \rho), & k_3 &= -(\rho + \delta + \tau), \\ k_4 &= \left[(\rho + \delta + \tau) - \frac{\sigma \beta S}{(\rho + \sigma)} \right], & k_5 &= -(\rho + \varphi) \;. \end{split}$$

From κ_4 it is easy to verify that our reproduction number is less than unity (1), Note that k_4 can be written as;

$$k_4 = \left[(\rho + \delta + \tau) - \frac{\sigma \beta S}{(\rho + \sigma)} \right] \le -(\rho + \delta + \tau)(1 - R_0) \tag{11}$$

From (11) it suffices that $K_4 < 0$ if $R_0 < 1$. Therefore, the negativity of all the eigenvalues implies the stability of the system.

2.5 Global stability of D.F.E

$$\frac{dS}{dt} = \lambda - \rho S + \phi R$$

$$\frac{dE}{dt} = \varphi S - \rho E - \sigma E$$

$$\frac{d\varphi}{dt} = \sigma E - \varphi (\gamma_1 + \gamma_2) - \rho \varphi$$

$$\frac{dI}{dt} = \gamma_2 \varphi - I(\rho + \delta) - \tau I$$

$$\frac{dF}{dt} = \gamma_1 \varphi - \tau I - R(\rho + \varphi)$$
(12)

Let
$$X = \{S\}, Y = \{E, \varphi, I\}.$$

- 1. We say the point $E^0 = \{X^0, 0\}$ is stable asymptotically if $R_0 \prec 1$ and the following two conditions are satisfied.
- 2. $\frac{dX}{dt} = F[X,0]$, then E^0 is asymptotically stable globally.
- 3. There exist G[X,Y] = Dy - G(x,y); $G(x,y) \ge 0$ for the first condition.

$$\frac{dS}{dt} = \lambda - \rho S \rightarrow \frac{dS}{dt} + \rho S = \lambda \text{ which is}$$

solvable by integrating factor methods such as;

$$Se^{\rho t} = \int_{0}^{t} \lambda \cdot e^{\rho t} dt + c \rightarrow Se^{\rho t} = \frac{\lambda}{\rho} e^{\rho t} + c \rightarrow S(t) = \frac{\lambda}{\rho}$$

as $t \rightarrow \infty$.

The first condition is satisfied. X_0 is globally asymptotically stable.

The Second Condi

$$G(x, y) = \begin{bmatrix} \varphi S - E(\varphi + \sigma) \\ \sigma E - \varphi(\gamma_1 + \gamma_2 + \rho) \\ \gamma_2 \varphi - I(\rho + \delta + \tau) \end{bmatrix}$$

$$A(G,x,y) = \begin{bmatrix} \frac{dF_1}{dE} & \frac{dF_1}{dQ} & \frac{dF_1}{dI} \\ \frac{dF_2}{dE} & \frac{dF_2}{dQ} & \frac{dF_2}{dI} \\ \frac{dF_3}{dE} & \frac{dF_3}{dQ} & \frac{dF_3}{dI} \end{bmatrix} = \begin{bmatrix} -(\rho+\sigma) & 0 & \beta S \\ \sigma & -(\gamma_1+\gamma_2+\rho) & 0 \\ 0 & \gamma_2 & -(\rho+\delta+\tau) \end{bmatrix}$$

$$= \begin{bmatrix} -(\mu_H + \theta_H) & 0 & BS \\ \theta_H & -(\alpha_1+\alpha_2+\mu_H) & 0 \\ 0 & \alpha_2 & -(\mu_H + \delta+\tau) \end{bmatrix}$$
Substituting the values of P_1, P_2, P_3 and P_4 into the equation
$$E[\Delta x] = P_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + P_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} + P_3 \begin{bmatrix} -1 \\ 0 \end{bmatrix} P_4 \begin{bmatrix} 0 \\ -1 \end{bmatrix} = \begin{bmatrix} P_1 - P_2 + P_3 \\ P_2 - P_4 \end{bmatrix}$$

$$= \begin{bmatrix} -(\mu_H + \theta_H) & 0 & BS \\ \theta_H & -(\alpha_1 + \alpha_2 + \mu_H) & 0 \\ 0 & \alpha_2 & -(\mu_H + \delta + \tau) \end{bmatrix}$$
(13)

Since
$$S = N = \frac{\lambda}{\rho}$$
, this implies $\hat{G}(x, y) = \begin{bmatrix} \beta \frac{\lambda}{\rho} S^0 - S \\ 0 \\ 0 \end{bmatrix}$

Obviously, $G(x, y) \ge 0$, Since $S \ge 0$ The Ebola virus can now be completely eradicated from the human population, ensuring global stability.

2.6. Transition probability using stochastic differential

The resulting stochastic differential equation has the following

$$dX(t) = F(x(t), t)dt + g(x(t), t)dt$$
(14)

Where; F(x(t),t) is the drift deterministic part of the model. g(x(t),t) is the diffusion part in which the transition probability is based.

$$F(x(t),t) = E\left(\frac{\Delta x}{\Delta \tau}\right)$$
 and $g(x(t),t) = E\left[\frac{\Delta x.(\Delta x)^T}{\Delta T}\right] = v^{\frac{1}{2}}$,

Since time is constant, S(t) and I(t) are continuous random variable.

Then
$$\Delta S = S(\Delta t + t) - S(t)$$
 and $\Delta I = I(\Delta t + t) - I(t)$

Let $X = [x_1, x_2]^T$, where x_1 and x_2 corresponds to S(t)and I(t) of the model.

We can formulate the transition probability from the deterministic part.

$$E(\Delta x) = \sum_{i=1}^{4} p_1 \Delta x_1 + p_2 \Delta x_2 + \dots p_n \Delta x_n.$$

Expectation

$$E[\Delta x.[\Delta x]] = \sum_{i=1}^{4} p_1 \Delta x_1.[\Delta x_1]^T + p_2 \Delta x_2.[\Delta x_2]^T + p_3 \Delta x_3.[\Delta x_3]^T + \dots$$

Co-variance.

Table 2: The transition probabilities

Potential Modifications	The likelihood (Probability)	Description (Details)
$\Delta x_1 = [1, 0]^T$	$\lambda S \Delta T$	Emergence of Susceptible
$\Delta x_2 = \begin{bmatrix} -1, +1 \end{bmatrix}^T$	$(\mu_H S + \theta_H E_H + \alpha_2 \theta) \Delta T$	Susceptible got infected
$\Delta x_3 = \begin{bmatrix} -1, 0 \end{bmatrix}^T$	$\mu_{\scriptscriptstyle H} S \Delta T$	Natural death of susceptible
$\Delta x_3 = [-1, 0]^T$	τ $l\Delta T$	Susceptible recovered

ubstituting the values of P_1, P_2, P_3 and P_4 into the equation

$$E[\Delta x] = P_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + P_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} + P_3 \begin{bmatrix} -1 \\ 0 \end{bmatrix} P_4 \begin{bmatrix} 0 \\ -1 \end{bmatrix} = \begin{bmatrix} P_1 - P_2 + P_3 \\ P_2 - P_4 \end{bmatrix}$$

$$E[\Delta x] = \begin{bmatrix} \lambda S \Delta T - (\rho S + \sigma E + \gamma_2 I - \rho S \Delta T) \\ (\rho S + \sigma E + \gamma_2 I) \Delta T - \tau I \Delta T \end{bmatrix}$$
(15)

For the covariance

$$\begin{split} E[\Delta x. \left[\Delta x\right]^T] &= P_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix}. \begin{bmatrix} 1 \\ 0 \end{bmatrix}. \begin{bmatrix} 1 \\ 0 \end{bmatrix} + P_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix}. \begin{bmatrix} -1 \\ 1 \end{bmatrix} + P_3 \begin{bmatrix} -1 \\ 0 \end{bmatrix}. \begin{bmatrix} -1 \\ 0 \end{bmatrix} + P_4 \begin{bmatrix} 0 \\ -1 \end{bmatrix}. \begin{bmatrix} 0 \\ 0 \end{bmatrix} - 1 \end{bmatrix} \\ E[\Delta x. \left[\Delta x\right]^T] &= P_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + P_2 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + P_3 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + P_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \\ E[\Delta x. \left[\Delta x\right]^T] &= \begin{bmatrix} P_1 + P_2 + P_3 & -P_2 \\ -P_2 & P_2 + P_4 \end{bmatrix} \\ E[\Delta x. \left[\Delta x\right]^T] &= \begin{bmatrix} \lambda S\Delta T + (\rho S + \sigma E + \gamma_2 I)\Delta T + \rho S\Delta T & -(\phi S + \rho E + \gamma_2 I) \\ -(\phi S + \sigma E + \gamma_2 I) & (\phi S + \sigma E + \gamma_2 I)\Delta T + \tau I\Delta T \end{bmatrix} \end{split}$$

Since
$$E\left[\frac{\Delta x}{\Delta T}\right] = F(x(t), t)dt$$
,
 $E\left[\frac{\Delta x.(\Delta x)^{T}}{\Delta T}\right] = V^{\frac{1}{2}} = g(x(t), t)$

Now we get
$$V^{\frac{1}{2}}$$
, $V^{\frac{1}{2}} = \frac{1}{\beta} \begin{bmatrix} \delta + \sigma & p \\ p & w + \sigma \end{bmatrix}$

Where

$$\sigma = \sqrt{\delta w - p^{2}} \qquad and \qquad \beta = \sqrt{\delta + w + 2\sigma}$$

$$\delta = (\lambda S + \rho)\Delta T + (\varphi S + \sigma E + \gamma_{2}I)\Delta T$$

$$p = -(\varphi S + \sigma E + \gamma_{2}I)\Delta T \qquad (16)$$

$$w = (\varphi S + \sigma E + \gamma_{2}I)\Delta T + \tau I\Delta T$$

Therefore,

$$(17)$$

$$\theta = \sqrt{\left[(\lambda S + \mu_{H}) + (\sigma S + \sigma E + \gamma_{2}I)\right]} (\varphi S + \sigma E + \gamma_{2}I) + \tau I \Delta T (\rho + \lambda) - P^{2}$$

$$\theta = \sqrt{\left[(\lambda S + \rho)(\varphi S + \sigma E + \gamma_{2}I) + (\lambda S + \rho)(\tau I) + (\varphi S + \sigma E + \gamma_{2}I)\right]}$$

$$\theta = \sqrt{\left[(\lambda S + \rho)(\varphi S + \sigma E + \gamma_{2}I) + \tau I(\varphi S + \sigma E + \gamma_{2}I) - P^{2} - P^{2}\right]}$$

$$\theta = \sqrt{\left[(\lambda S + \rho)(\varphi S + \sigma E + \gamma_{2}I) + (\varphi S + \sigma E + \gamma_{2}I)^{2} + (\lambda S + \rho)(\tau I)\right]}$$

$$Then.$$

$$\theta = \sqrt{\left[(\lambda S + \rho)(\varphi S + \sigma E + \gamma_{2}I) + \tau I(\varphi S + \sigma E + \gamma_{2}I) + (\lambda S + \rho)d\right]}$$

$$\beta = \sqrt{\delta + w + 2\sigma}$$

$$\beta = \sqrt{+(\varphi S + \sigma E + \gamma_{2}I) + (\varphi S + \sigma E + \gamma_{2}I) + \tau I + (\lambda S + \rho) + 2\sigma}$$

$$\beta = \sqrt{(\lambda S + \rho) + \tau I + 2(\varphi S + \sigma E + \gamma_{2}I) + 2\sigma}$$

Since F(x(t),t) & g(x(t),t) has been stated clearly then, the stochastic differential equation for the Ebola virus is given thus:

$$dX(t) = F(x(t),t) + g(x(t),t)dw(t)$$

Where $w(t) = w_1(t), w_2(t)$ represent independent Wiener's process for the compartment.

 $X(t) = [X_1, X_2]$, Where X_1 and X_2 translate S(t) and I(t). Therefore,

$$\frac{dS}{dt} = \left(S(\lambda - \rho) - (\varphi S + \sigma E + \gamma_2 I)dt\right) + \frac{\delta + \sigma}{\beta} dw_1(t) + \frac{p}{\beta} dw_1(t).$$

$$\frac{dI}{dt} = \left((\varphi S + \sigma E + \gamma_2 I) - \tau I \Delta T\right)dt + \frac{p}{\beta} dw_1(t) + \frac{w + \sigma}{\beta} dw_2(t).$$

Now we define

$$A(t) = \int_{0}^{t} \left(\frac{\delta + \sigma}{\beta}\right) dw_{1}(t) + \int_{0}^{t} \left(\frac{p}{\beta}\right) dw_{2}(t) = \int_{0}^{t} \left(\frac{\delta(S) + \sigma(S)}{\beta(S)}\right) dw_{1}(S) + \int_{0}^{t} \left(\frac{p(S)}{\beta(S)}\right) dw_{2}(S)$$

Hence.

$$\begin{split} \left\langle A(t) \right\rangle &= \int \left(\frac{\delta(S) + \sigma(S)}{\beta(S)} \right)^2 dS + \int_0^t \left(\frac{p(S)}{\beta(S)} \right)^2 dS = \int \left(\frac{\delta(S)^2 + 2\delta(S)\sigma(S) + \sigma(S)^2 + p(S)^2}{\beta(S)^2} \right) dS \\ &= \int \left[\left(\lambda S + \rho S \right) + \left(\rho S + \sigma S + \gamma_2 I \right) \right]^2 + 2(\lambda S + \rho)(\sigma(S)) - \left(\rho + \sigma E + \gamma_2 I \right)^2 \\ &+ \sqrt{(\lambda S + \rho S)(\varphi + \sigma S + \gamma_2 I) + \tau I(\lambda S + \rho S) + (\varphi S + \sigma E + \gamma_2 I)^2} \\ &+ (\varphi S + \sigma E + \gamma_2 I)^2 + \left(\sqrt{(\lambda S + \rho S) + \tau I + 2(\varphi S + \sigma E + \gamma_2 I) + 2\sigma} \right)^2 \\ &= \left[S(\lambda + \rho) + (\rho S + \sigma E + \gamma_2 I) \right] + \left(\sqrt{(\lambda S + \rho S) + \tau I + 2(\varphi S + \sigma E + \gamma_2 I) + 2\sigma} \right)^2 \end{split}$$

Hence,
$$A(t) = \int_{0}^{t} S(\lambda + \rho) + (\rho S + \sigma E + \gamma_2 I) \ dw(S)$$
 (18)

As a result,

$$dS(t) = \left(S(\lambda + \rho) - (\rho S + \sigma E + \gamma_2 I)\right)dt + \sqrt{S(\rho + \lambda) + (\rho S + \sigma E + \gamma_2 I)dw(t)}$$

The same process can be applied to the second equation.

$$\frac{dI}{dt} = ((\varphi S + \sigma S + \gamma_2 I) - \tau I)dt + \sqrt{((\rho S + \sigma E + \gamma_2 I) + \tau I)dw(t)}$$

Therefore, the system of stochastic differential equations for the Ebola virus describes how the population's susceptibility and infection vary over time.

Nevertheless, the stochastic differential equation can more accurately represent the framework (system):

$$\frac{dI}{dt} = ((\varphi S + \sigma S + \gamma_2 I) - \tau I)dt + \sqrt{((\rho S + \sigma E + \gamma_2 I) + \tau I)dw(t)}$$
Hence, $S(t) + I(t) = N(t) > 0$

3 RESULTS AND DISCUSSION

3.1. Numerical Solution

Solving the sets of differential equations used to model the Ebola virus numerically, we make use of the Finite Difference Scheme (FSD) to decompose model (1) to yield.

$$\frac{S_{j+1} - S_{j}}{h} = \lambda - (\rho + \Psi)S_{k} + \varphi R$$

$$\frac{E_{j+1} - E_{j}}{h} = \Psi S - (\rho + \sigma)E_{k}$$

$$\frac{Q_{j+1} - Q_{j}}{h} = \sigma E - (\gamma_{1} + \gamma_{2} + \rho)Q_{k}$$

$$\frac{I_{j+1} - I_{j}}{h} = \gamma_{2}Q - (\rho + \delta + \tau)I_{k}$$

$$\frac{R_{j+1} - R_{j}}{h} = \gamma_{1}Q + \tau I - (\rho + \phi)R_{k}$$
(19)

Equation (19) can alternatively be written as;

$$\begin{split} S_{j+1} &= S_j + h(\lambda - (\rho + \Psi)S_k + \varphi R) \\ E_{j+1} &= E_j + h(\Psi S - (\rho + \sigma)E_k) \\ Q_{j+1} &= Q_j + h(\sigma E - (\gamma_1 + \gamma_2 + \rho)Q_k) \\ I_{j+1} &= I_j + h(\gamma_2 Q - (\rho + \delta + \tau)I_k) \\ R_{j+1} &= h(\gamma_1 Q + \tau I(\rho + \phi)R_k) \end{split} \tag{20}$$

Where j = 0, 1, 2, 3, 4, 5..., h is the step size

3.2 Numerical Simulation

To check the overall dynamics of the effect each parameter on the population model, the Matrix Laboratory (MATLAB) was used in simulation along the side Table 2, which contains parameters and their values.

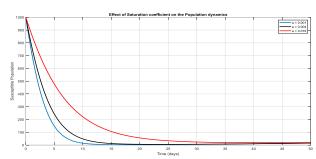


Figure 2: Trajectories solution of saturated coefficient on the susceptible population

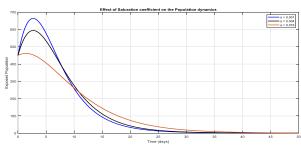


Figure 3: Trajectories solution of saturated coefficient on the exposed population.

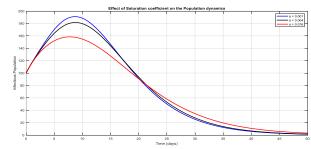


Figure 4: trajectories solution of saturated coefficient on the infected population

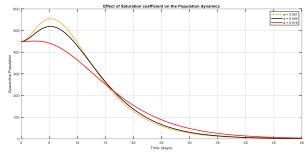


Figure 5: trajectories solution of saturated coefficient on the quarantine population

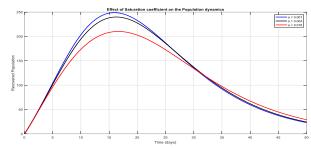


Figure 6: trajectories solution of saturated coefficient on the recovered population

Figure (2-6) demonstrate the effect of saturation on the population density for susceptible, exposed, infected, quarantine and the recovered class respectively. The results indicate that the higher the saturation the faster the infection leaves it host community, which in turn leads to stability on the population density, which indicates that we can have a disease-free equilibrium state in the proposed community if saturation as a form of treatment is well implemented. Government officials, policy makers and health organizations are best informed of the best treatment to implement to finally cure the population of EVD.

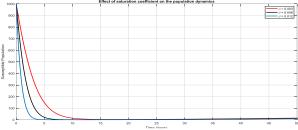


Figure 7: trajectories solution of effective contact rate on the susceptible population

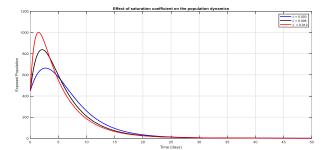


Figure 8: trajectories solution of effective contact rate on the exposed population

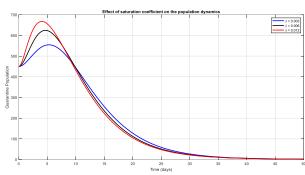


Figure 9: Trajectories solution of effective contact rate on the quarantine population

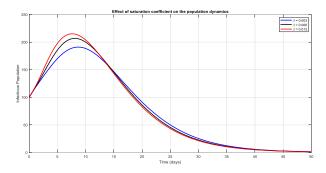


Figure 10: Trajectories solution of effective contact rate on the infectious population

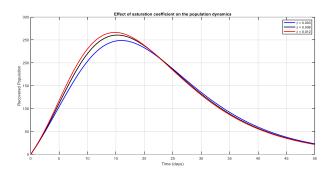


Figure 11 Trajectories solution of effective contact rate on the recovered population.

Figures (7-11) illustrate the effect of contact rate β on all compartments within the proposed model. Results show that the higher the contact rate the more the people get infected, which means that the reproduction number of (EVD) will be greater than unity (1) which later lead to higher mortality in the population. This demonstrates the negative impact the contact rate of the disease could have on the population when not controlled. The infection could become endemic if proper saturation factor as a form of treatment is not considered.

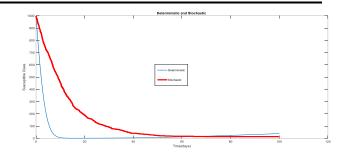


Figure 12: The dynamics of deterministic and stochastic in the susceptible population

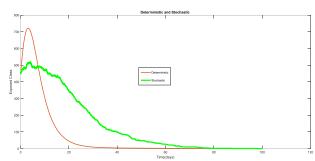


Figure 13: The dynamics of deterministic and stochastic in the exposed population

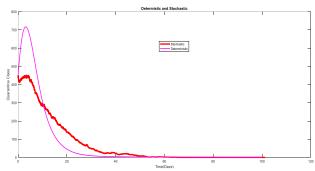


Figure 14: The dynamics of deterministic and stochastic in the quarantine population.

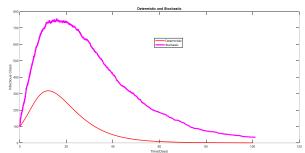


Figure 15: The dynamics of deterministic and stochastic in the infected population.

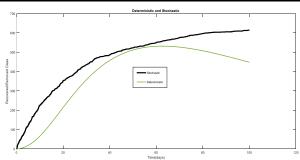


Figure 16: The dynamics of deterministic and stochastic in the removed/recovered population.

Figure (12-16) simply demonstrates the dynamics of stochastic model as an approximation of the deterministic of the model in the long run considering randomness of events in each compartment.

CONCLUSION

This research proposed a modified SEQIR dynamical model to investigate the effect of saturation factors and effective contact rate on the transmission dynamics of Ebola virus and results show that proper control plans can achieve a lower mortality rate in the community. When saturation factor is reduced and contacts among susceptible individuals are impaired, then transmission of the deadly virus is observed to dwindle and get exterminated in the final analysis.

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Conflict of Interest

The authors declare that no funds, grants or other support were received for the preparation of this manuscript. The authors also declare no conflict of interest.

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